# **Up/Down Counter/Timer**

# DIN W72×H36mm of Counter/Timer with indication only

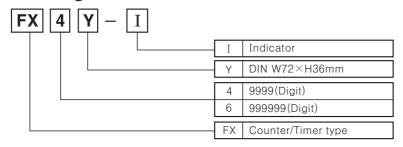
#### Features

- •Upgraded counting speed: 1cps/30cps/2kcps/5kcps
- Application of Up/Down input mode
- •Selectable Up/Down indication of display value
- ●Wide range of input power supply: 100-240VAC 50/60Hz, 12-24VAC/DC
- •Selectable Counter or Timer function by internal DIP switch
- •Selectable time ranges
- •Built-in Microprocessor





# Ordering information



# Specifications

Model		FX4Y-I FX6Y-I			
Digit		4	6		
Digit size		W8×H14mm	W4×H8mm		
Power sup	ply	100-240VAC 50/60Hz, 12-24VAC/DC (Option)			
Allowable voltage range		90 ~ 110% of rated voltage			
Power consumption		Approx. 4.5VA(240VAC 60Hz), Approx. 4.5VA(24VAC 60Hz), Approx. 2.5W(24VDC)			
Max. coun	ting speed	Selectable 1cps/30cps/2kcps/5kcps by internal DIP switch			
Min. input INHIBIT input signal width RESET input		Min. 20ms			
Input	CP1, CP2 input RESET input	No voltage input Impedance at short-circuit: Max. 470Ω, Residual voltage at short-circuit: Max. 1VDC, Impedance at open-circuit: Min. 100kΩ			
Memory pr	otection	10 years(When using non-volatile semiconductor memory)			
Eexternal power		12VDC±10% 50mA Max.			
Insulation resistance		Min. 100MΩ (at 500VDC mega)			
Dielectric strength		2000VAC 50/60Hz for 1 minute			
Noise	AC Type	±2kV the square wave noise(pulse	e width:1μs) by the noise simulator		
strength	DC Type	$\pm 500 \mathrm{V}$ the square wave noise(puls	se width:1µs) by the noise simulator		
Vibration	Mechanical	0.75mm amplitude at frequency of 10 $\sim$ 55Hz in each of X, Y, Z directions for 1hour			
vibration	Malfunction	0.5mm amplitude at frequency of 10 $\sim$ 55Hz in each of X, Y, Z directions for 10 minute			
Shock	Mechanical	300m/s² (Approx. 30G) in X, Y, Z directions for 3 times			
OHOCK	Malfunction	100m/s <sup>2</sup> (Approx. 10G) in X, Y, Z directions for 3 times			
Ambient te	mperature	-10 ~ +55℃ (at non-freezing status)			
Storage te	mperature	-25 ~ +65 ℃ (at non-freezing status)			
Ambient humidity		35 ~ 85%RH			
Life cycle		Semi-permanent			
Unit weigh	t	AC type:Approx. 126g, DC type:Approx. 130g AC type:Approx. 128g, DC type:Approx. 132g			
Approval		c <b>521</b> us			

(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/ Speed/ Pulse meter

(G) Display unit

(H) Sensor controller

Switching power supply

(J) Proximity sensor

(K) Photo electric sensor

(L) Pressure sensor

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

(O) Graphic panel

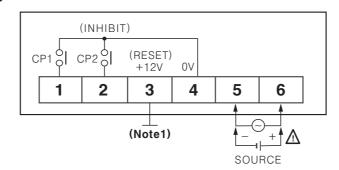
(P) Field network device

(Q) Production stoppage models & replacement

Autonics A-30

# **FXY Series**

#### Connections



\*(Note 1) It can be selected RESET or sensor power(+12VDC 50mA) by internal PIN operation. (Refer to A-35) \*CP1, CP2: Input signal terminals when using as Counter.

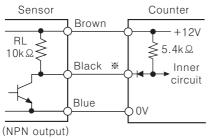
※INHIBIT(CP2): Time Hold terminal when using for timer(Connect switch to ②+④ from the external.)

\*Operated by a Power ON Start method when it is used as a timer.

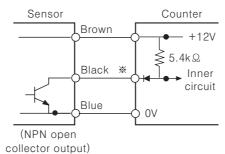
## Input connections

OUsing for no-voltage input(NPN)

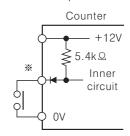
•Solid-state input(Standard sensor: NPN output type sensor)







Contact input

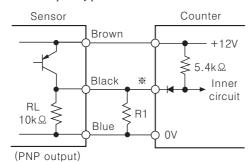


\*Please select the counting speed as 30cps when using for counter.

### OUsing for voltage input(PNP)

FXY series is for no-voltage input type, it is not available to count applying DC voltage from the external. For using PNP type sensor, please use as the following to count.

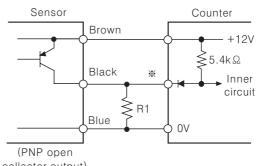
●PNP output type sensor



•Please set R1 value to make the composed resistance of RL + R1 as Max.  $470k\Omega$  is an impedance for short-circuit.

**\*CP1**, CP2(INHIBIT), RESET input

•PNP open collector output type sensor



collector output)

※In case of PNP open collector output type sensor, please connect lower than  $470\,\Omega$  of R1 to input terminal before using.

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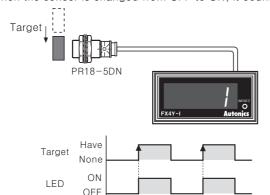
# **Up/Down Counter/Timer**

# ■ Counting method

Be careful to select sensor because the counting method of NPN output type sensor is different from PNP output type sensor.

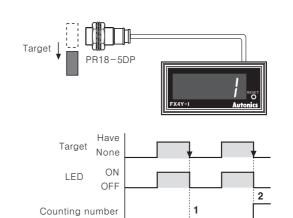
●NPN output type sensor

When the sensor is changed from OFF to ON, it counts.



●PNP output type sensor

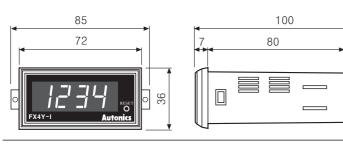
When the sensor is changed from ON to OFF, it counts.



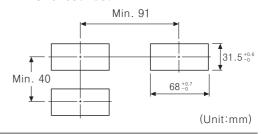
n

## Dimensions

Counting number



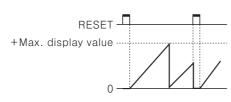
●Panel cut−out



# Counting operation of indication type(Counter)

2

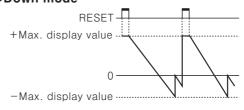
Up mode



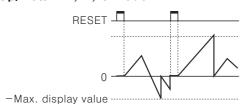
●Down mode

30

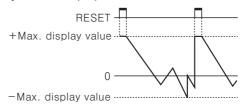
13



●Up/Down-A, B, C Mode

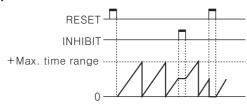


●Up/Down-D, E, F Mode

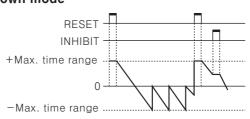


## Counting operation of indication type(Timer)

●Up mode



●Down mode



(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/ Speed/ Pulse meter

(G) Display unit

(H) Sensor controller

(I) Switching power supply

(J) Proximity sensor

(K) Photo electric sensor

(L) Pressure sensor

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

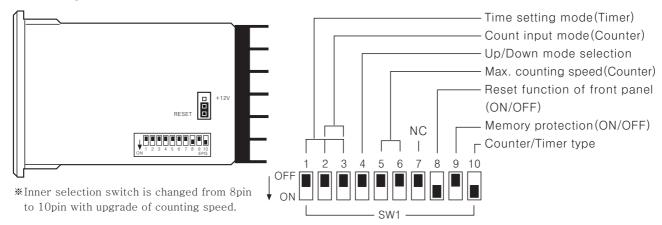
(O) Graphic panel

(P) Field network device

(Q) Production stoppage models & replacement

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# **■** Description of inner DIP switches



## ●Up/Down mode

	SW1	Function	
1	OFF ON	Up mode	
4	OFF ON	Down mode	

### Reset function of front panel(ON/OFF)

SW1		Function		
8	OFF ON	Disable the front panel reset function		
	OFF ON	Enable the front panel reset function		

## Memory protection (ON/OFF)

SW1		Function		
a	OFF ON	Enable the memory protection		
Э	OFF ON	Disable the memory protection		

### Counter/Timer selection

	SW1	Function	
10	OFF ON	Timer	
10	OFF ON	Counter	

#### Max. counting speed

SW1	CP1, CP2	
5 6 OFF ON	1cps	
OFF ON	30cps	
5 6 OFF ON	2kcps	
5 6 OFF ON	5kcps	

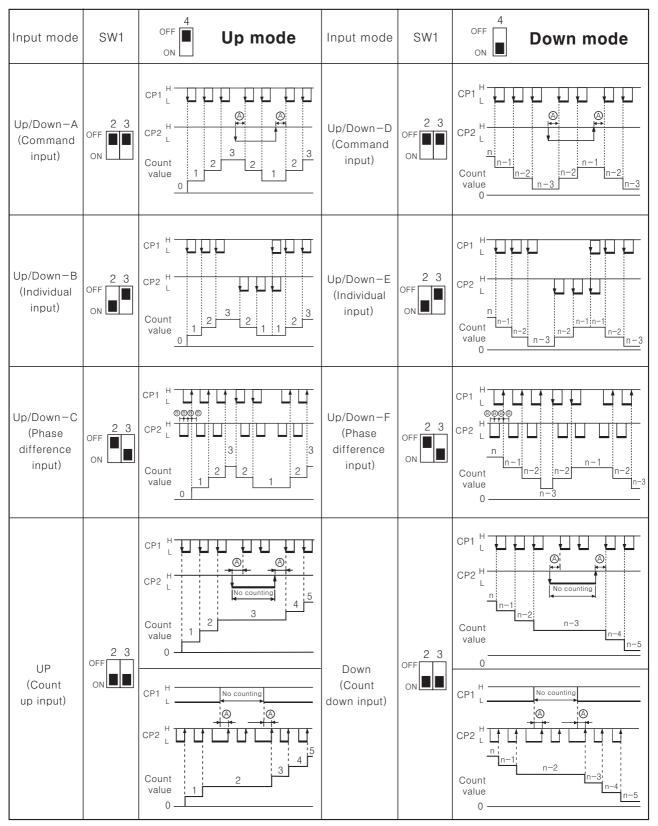
# ■Time setting mode(Timer)

SW1	4Digit	6Digit	SW1	4Digit	6Digit
OFF ON	99.99sec	99999.9sec	1 2 3 OFF ON	999.9min	99999.9min
B 1 2 3 OFF ON	999.9sec	999999sec	1 2 3 OFF ON	99hour 59min	99hour 59min 59sec
OFF ON	9999sec	99min 59.99sec	G 1 2 3 OFF ON	999.9hour	9999hour 59min
OFF 1 2 3	99min 59sec	999min 59.9sec	H 1 2 3 OFF ON	9999hour	99999.9hour

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# **Up/Down Counter/Timer**

# **■Input mode(Counter)**



**※** ○ : Over Min. signal width, ○ : Over 1/2 of Min. signal width.

If the signal width of a or b is less than min. signal width,  $\pm 1$  of count error is occured.

\*n: + Max.display value(FX4Y-I: 9999, FX6Y-I: 999999)

(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

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(N) Stepping motor & Driver & Controller

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(P) Field network device

(Q) Production stoppage models & replacement

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#### ■ Proper usage

#### **O**Reset

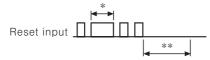
Reset

When selecting a reset input/output mode, please apply the external reset or manual reset signal.

# If it is not reset, it is operated as the prior mode.

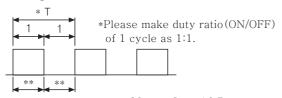
•Reset signal width

It is reset perfectly when the reset signal is applied for **max. 20ms** regardless of the contact input & solid-state input.



- \*In case of a contact reset, it is reset perfectly if the ON time of reset signal is applied for max. 20ms even though a chattering is occured.
- \*\*Signal input (CP1, CP2) is possible if there is no reset input for min. 50ms after reset input.

### OMin.signal width

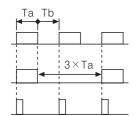


\*\* Min. signal width [ 30cps : Over 16.7ms 2kcps : Over 0.25ms

#### Maximum counting speed

This is a response speed per 1 sec. when the duty ratio(ON:OFF) of input signal is 1:1.

If the duty ratio is not 1:1, the width between ON and OFF should be over min. signal width and the response speed will getting slower against input signal. And one of ON width and OFF width is under min.signal width, this product may not response.



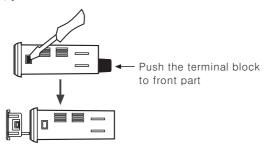
Ta(ON width) and Tb(OFF width) need to be over min. signal width.

When duty ratio is 1:3, the max. counting speed will be 1/2 from the rated spec.

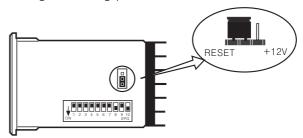
This product does not respond.

### ODetach the case from body

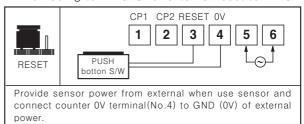
While pushing the Lock part with with driver to the front, push the terminal block.



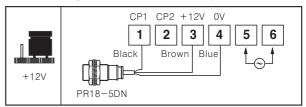
#### OUsing switching pin of Reset / +12V



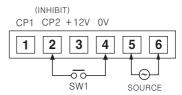
#### •When using terminal 3 for external reset terminal



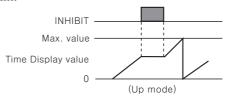
#### •When using terminal 3 for sensor power terminal



#### OINHIBIT[For Timer]



- •It becomes the INHIBIT mode when SW1 turns on. (Time Hold)
- •When power is applied, it starts to progress and INHIBIT mode is used to stop the time is under the progress at the moment.
- •When SW1 is OFF, timer starts to progress again.



#### OPower

The inner circuit voltage starts to rise up for the first 100ms after power on, the input may not work at this time. And also the inner circuit voltage drops down for the last 500ms after power off, the input may not work at this time.



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